

What Is Claimed Is:

1. A vehicle system (1) for operation in a motor vehicle having
an operator control (15) for operating the vehicle system (1), and
a controller (12) for influencing operation of the vehicle system via the operator control (15),
wherein a device (11) is provided which is designed for detecting whether the driver (2) or another occupant (3) of the vehicle has operating access to the operator control, and
the controller (12) is designed for influencing the operation of the vehicle system (1) via the operator control (15) at least as a function of whether the operator control (15) is being accessed by the driver (2) or another occupant (3) of the vehicle.
2. The vehicle system as recited in Claim 1,
wherein it has a device (16) for determining a motion status of the motor vehicle, and the controller (12) is designed for influencing the operation of the vehicle system (1) via the operator control (15) additionally as a function of a detected motion status of the vehicle.
3. The vehicle system as recited in Claim 1 or 2,
wherein the controller (12) is designed for limiting the operation via the operator control (15) if it is determined that the vehicle is in motion and the operator control is being accessed by the vehicle driver (2).
4. The vehicle system as recited in one of the preceding claims,
wherein the access detection means (11) includes a video sensor system, in particular a camera (115), whose image detection range includes at least the driver seat (2) or

the front-seat passenger seat (3), preferably both the driver and the front-seat passenger seat.

5. The vehicle system as recited in Claim 4, wherein the access detection means (11) includes a stereo or multicamera video sensor.
6. The vehicle system as recited in Claim 4 or 5, wherein the access detection means (11) is designed for including the gray-scale value information contained in the video sensor signals in the analysis thereof.
7. The vehicle system as recited in one of Claims 1 through 3, wherein the access detection means (11) includes a radar sensor system.
8. The vehicle system as recited in one of Claims 1 through 3, wherein the access detection means (11) includes at least one depth sensor which works according to the propagation time principle.
9. The vehicle system as recited in one of Claims 1 through 3, wherein the access detection means (11) includes at least one depth sensor which works according to the laser scanner principle.
10. The vehicle system as recited in one of Claims 1 through 5, wherein the access detection means (11) includes at least one depth sensor which works according to the structured lighting principle.